

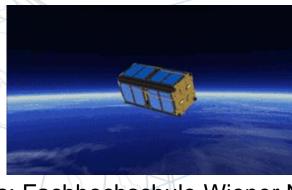
# **Electric propulsion as game changer for CubeSat: mission analysis with LOTOS**

Space Tech Expo Europe 24 October 2017, Bremen (DE)

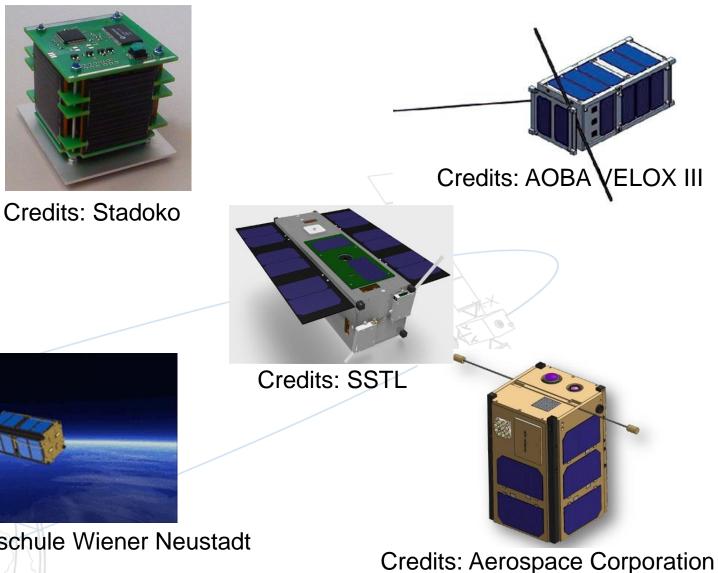
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#### **Outline**

- Astos Solutions and Products
- State of art
- **Motivation**
- EP for orbit change
- Orbit change examples
  - Micro satellite •
  - Cubesat
  - Space tug example
  - LOTOS
  - Introduction
  - **Operational mode**
  - Conclusion



Credits: Fachhochschule Wiener Neustadt



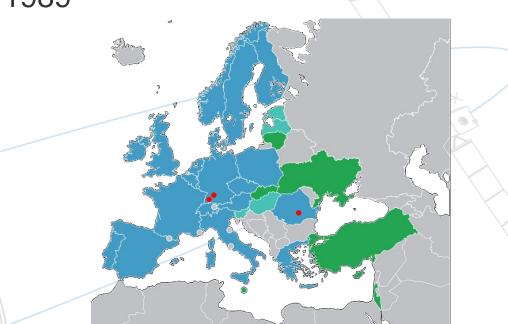
#### **Astos Solutions overview**



- SME with sites in Unterkirnach (DE), Stuttgart (DE), Bucharest (RO)
- Spin-Off of the Univ. of Stuttgart, standalone company since 2006
- Roots of Astos Solutions go back to 1989

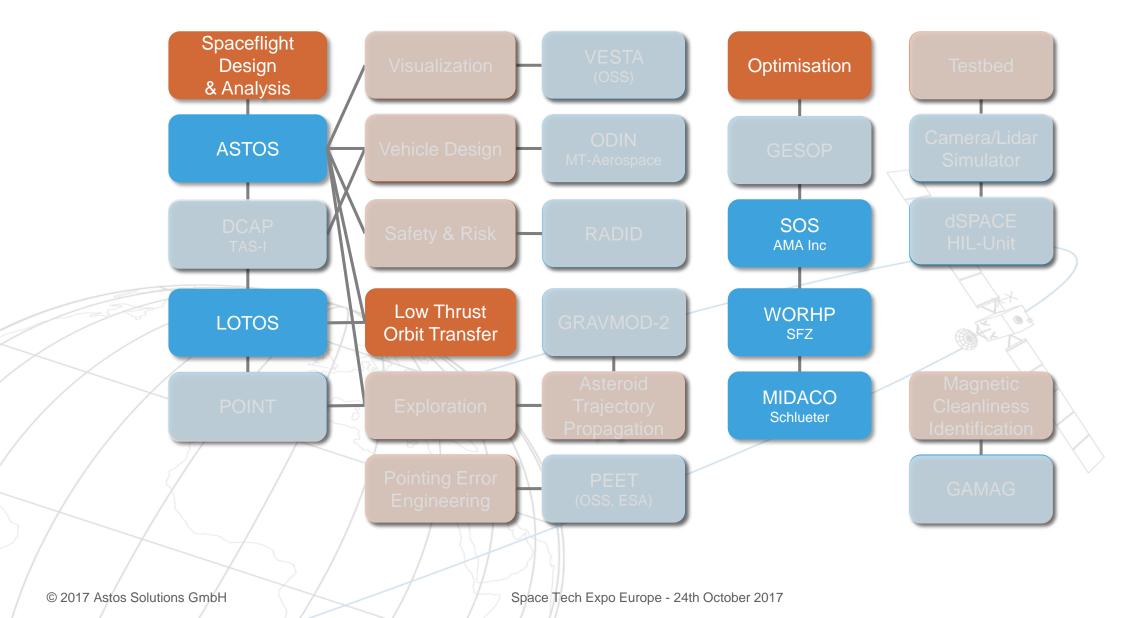


Office in Stuttgart



#### **Product overview**





# State of the art – Propulsion



What about Cube-sat and Micro-sat?:

- Several commercial options
  - BUSEK
  - Aerojet Rocketdyne
  - Accion Systems
  - Sitael

Others ...



Credits: Aerojet Rocketdyne

Credits: Accion Systems

University studies and test (e.g. MIT, Michigan)



Credits: Sitael

#### **State of the art – Application**



Low-thrust is used in space:

- Orbit change till target orbit (GTO-GEO)
- Position and Attitude control during operational phase
- De-orbit or graveyarding at end-of-life

Near future scenarios:

- Orbit change till target orbit (after piggy-back)
- Space tug for delivery and service

Credits: Astos Solutions LOTOS

#### **Motivation**

Astos

All these scenarios requires:

- Optimization and analysis of high-fidelity transfer trajectories
- Optimized maneuver planning
- Software for Guidance & Navigation
- Mission analysis

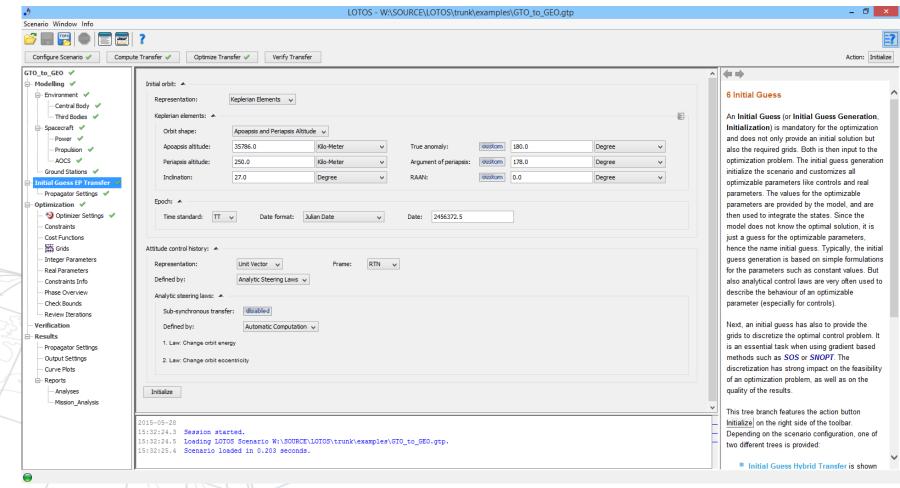
Is there budget/time for development of in-house tools?

BIa BIa Car STAY AWAKE IT'S CODING NIGHT

# **COTS solution – LOTOS**



- Hybrid transfers
- Electric transfer
- Controlled 6DoF attitude
- Verification of trajectories
  - Database
- Post-processing
- Reports
- Windows & Linux platform



# **LOTOS – operational aspects**



Once the trajectory (and satellite) is optimized, operational aspects have to be considered:

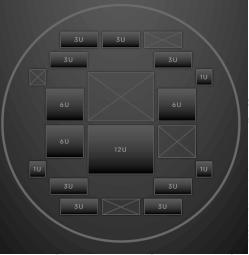
- Re-optimization of trajectory after separation from launcher to consider injection errors.
- Periodic re-optimization of trajectory to account for perturbations, attitude errors and underperformance of **Spacecraft Operations EOR Software** propulsion. Centre New maneuver plan of next **Reference Trajectory** Position, Velocity, Mass cycle is uploaded to the **Orbit Determination Initial State Update** satellite. **Re-Optimization** Manoeuvre Plan (CCSDS) **Ground Software** Verification Credits: Safran

# **Electric Propulsion for orbit change – Example**



Several satellites are launched in a single orbit:

- PSLV
- Soyuz
- Even more in the future (Falcon, Electron, etc.)





Credits: Glavkosmos

Credits: Rocket Lab

# **EP for orbit change – Microsat example**

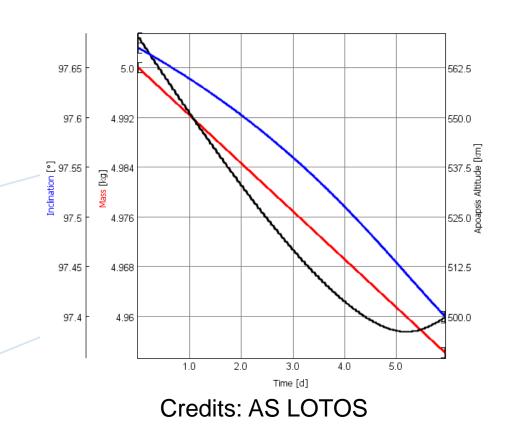


- PLSV delivery at 800 km SSO  $\rightarrow$  Not compliant with end-of-life regulations.
- Target orbit 500 km SSO 98.6 50.2 850.0 Satellite mass 50 kg 98.4 50.0 800.0 • Power = 200 W • Isp = 1400 s (Hall) 98.2 49.8 750.0 Ē Thrust = 0.013 N 98.0 Indination 돌 <sup>49.6</sup> 700.0 문 49.4 650.0 뮹 Final Sat mass = 48.9 kg 97.6 49.2 600.0 Transfer duration = 12.8 days 97.4 49.0 550.0 Delta V = 291 m/s97.2 48.8 500.0 2.0 4.0 6.0 8.0 10.0 12.0 Time [d] Credits: AS LOTOS

# EP for orbit change – 3U Cubesat example



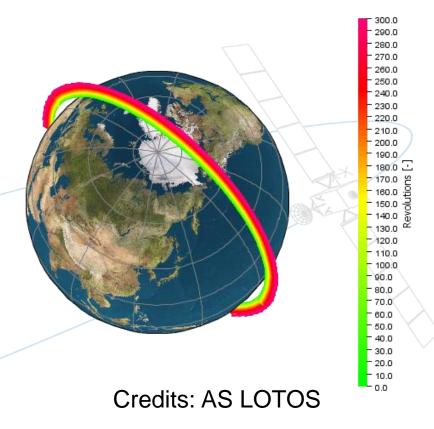
- PLSV delivery at 570 km SSO  $\rightarrow$  Not compliant with end-of-life regulations.
- Target orbit 500 km SSO
  - Satellite mass 5 kg
  - Power = 15 W
  - Isp = 800 s (Electrospray)
  - Thrust = 0.7 mN
  - Final Sat mass = 4.954 kg
  - Transfer duration = 5.9 days
  - Delta V = 72 m/s



# **Space tug – Cubesat/Microsat applications**



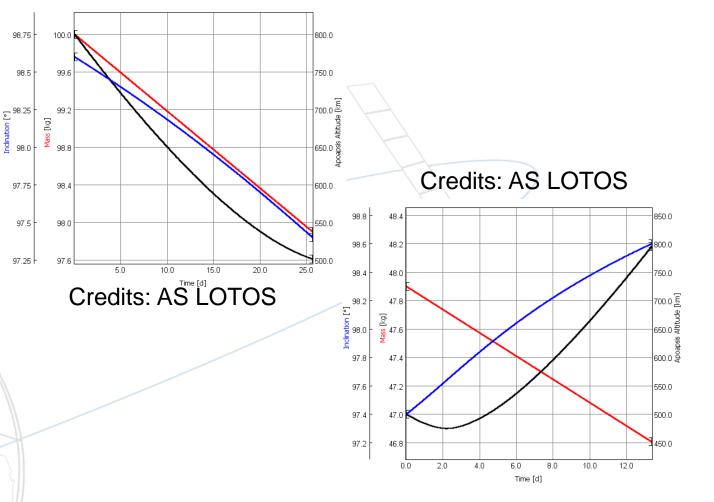
- Delivery of a satellite to its final orbit
- Constellation deployment without impacting life-time of satellites
- De-orbit of not active satellites
- Service of satellites in LEO for repositioning, life-extension, repair and graveyarding.



# **Space tug – Does it make sense?**



- Microsat example from 800 km to 500 km
  - Satellite mass 50 kg
  - Tug mass = 50 kg
  - Power = 200 W
  - Isp = 1400 s (Hall)
  - Thrust = 0.013 N
  - Final Tug mass = 47.9 kg
  - Transfer duration = 25.6 days
- Tug return to 800 km SSO
  - Final Tug mass = 46.8 kg
  - Transfer duration = 13.4 days



#### Conclusion



- Electric propulsion is a well proven technology, the miniaturisation of it allows the implementation on micro-satellites and cubesats.
- This allows constellation deployment, end-of-life grave yarding and modification of orbit parameters reached by piggy-back deployment.
- Preliminary trajectory optimizations show interesting results for micro-satellites and cubesats.
- Question: are the advantages repaid by the propulsion sub-system cost?
- The application of an electric propulsion Tug is questionable for micro-satellites, not interesting for cube-sat due to volume and mass limitations.

#### Conclusion



- The increased complexity of mission analysis and trajectory optimization requires experience and powerful tools for the design and operation of such vehicles.
- Question: what is cheaper and faster, in-house or COTS software?
- LOTOS can be a solution:
  - Simulation, optimization and analysis
  - Electric and hybrid transfer
  - It supports spacecraft operations



#### Leadership requires solutions

